

FIG.1(a)
(Prior Art)

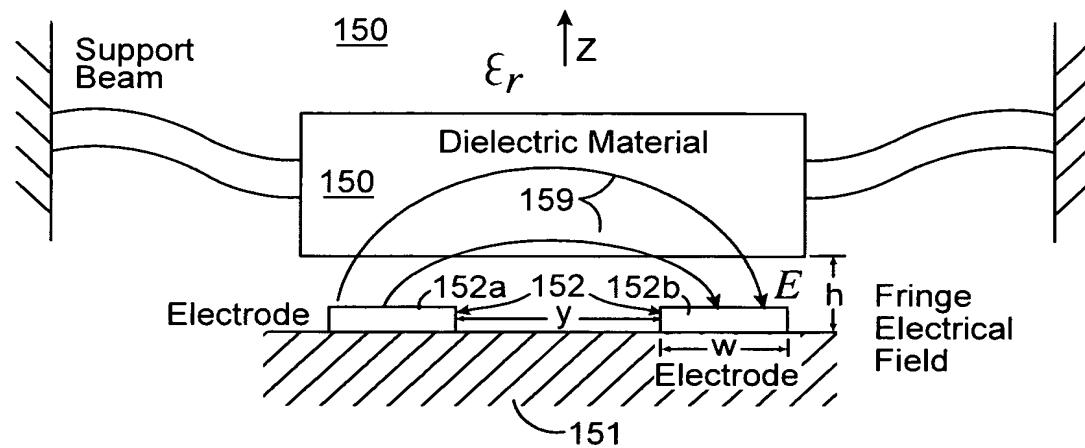


FIG.1(b)

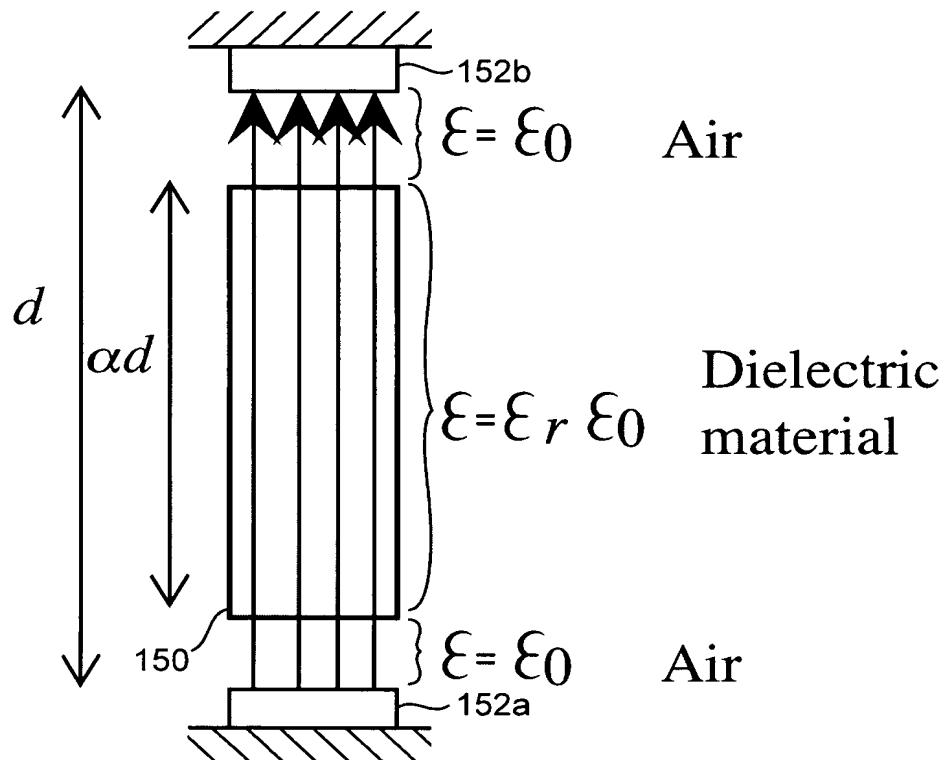


FIG.1(c)

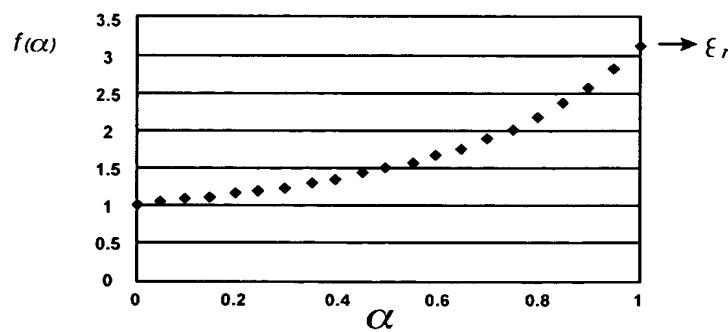


FIG.1(d)

3 / 11

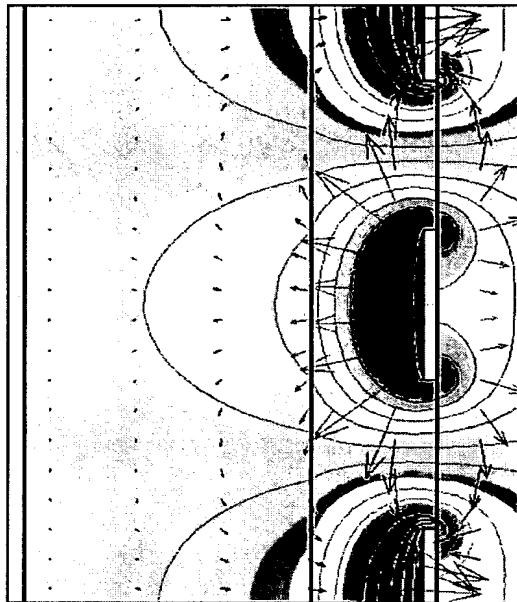


FIG.2(b)

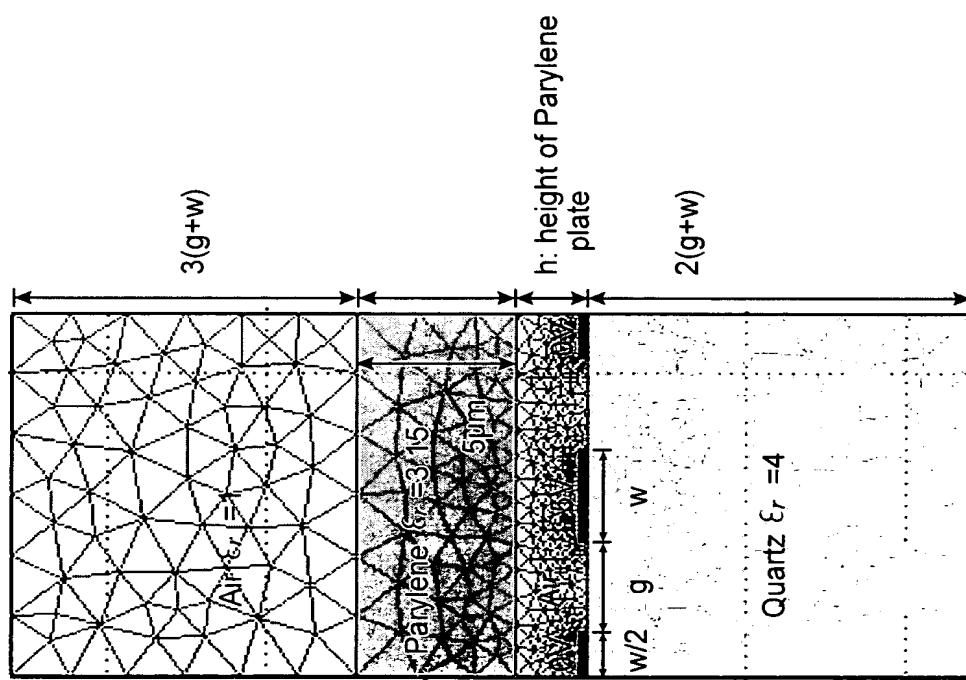


FIG.2(a)

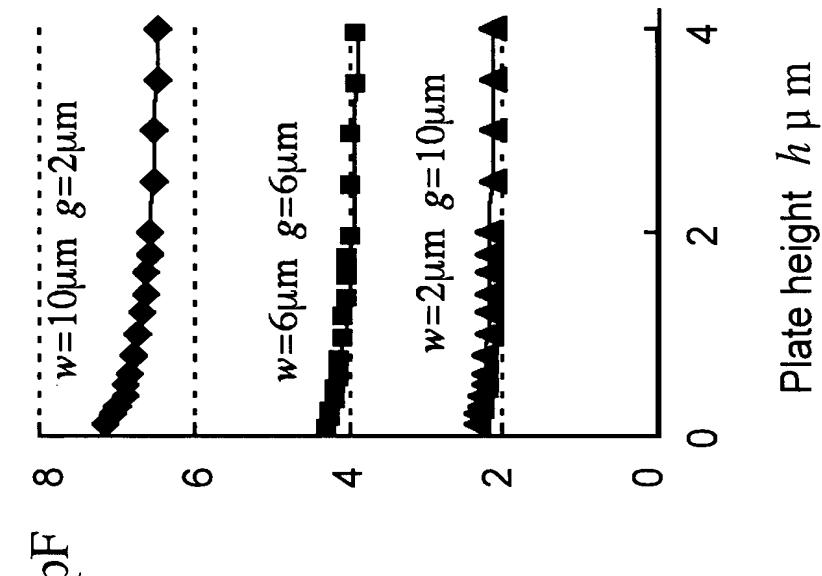


FIG.2(d)

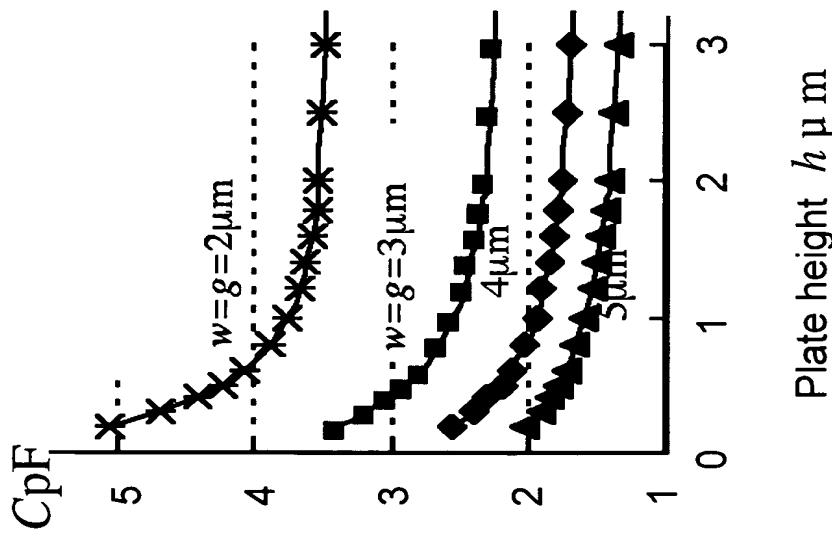
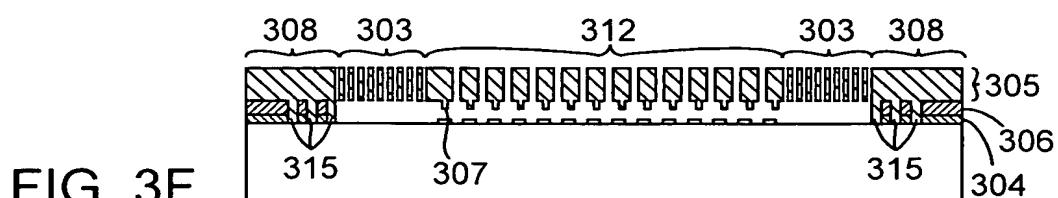
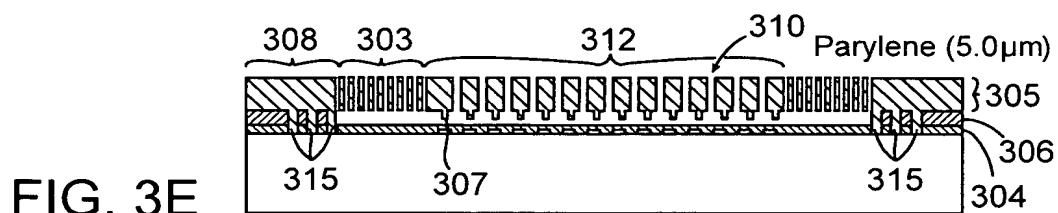
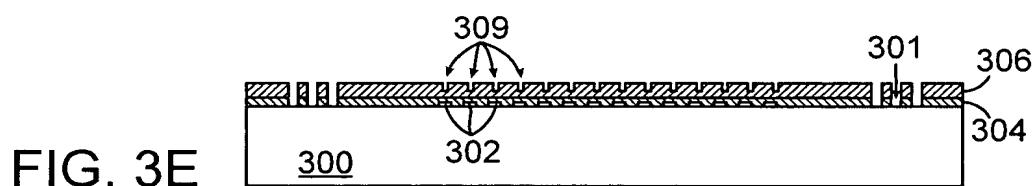
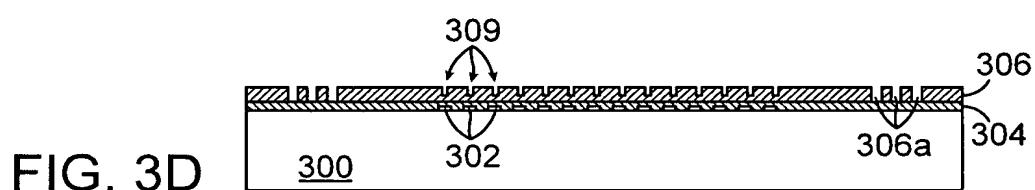
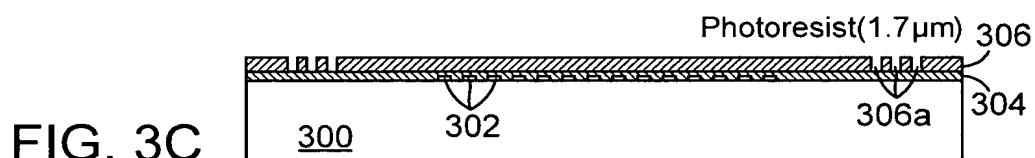
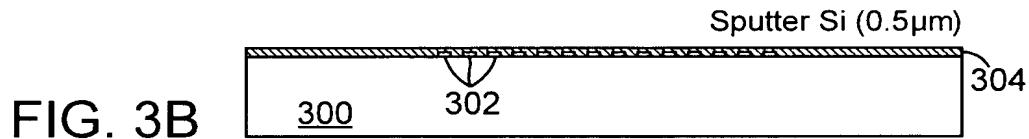
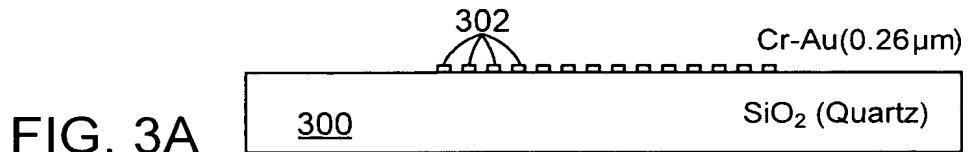


FIG.2(c)

5 / 11



6 / 11

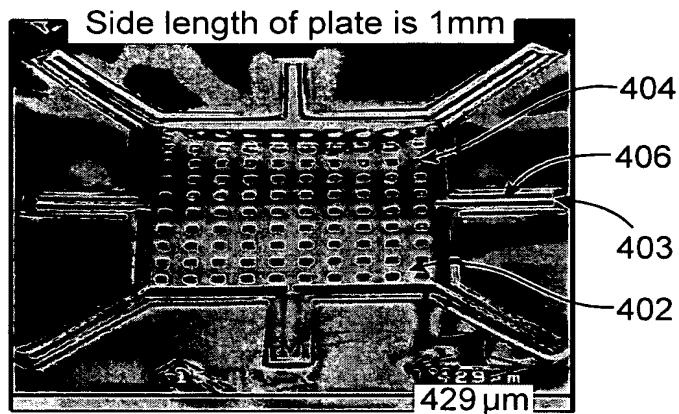


FIG. 4(a)

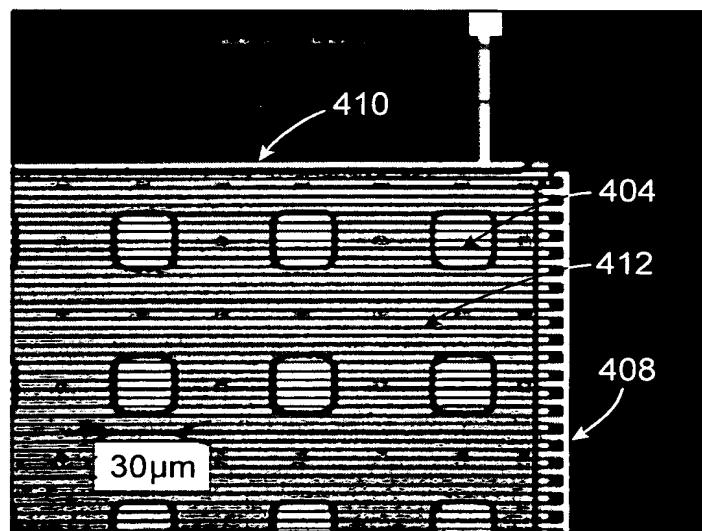


FIG. 4(b)

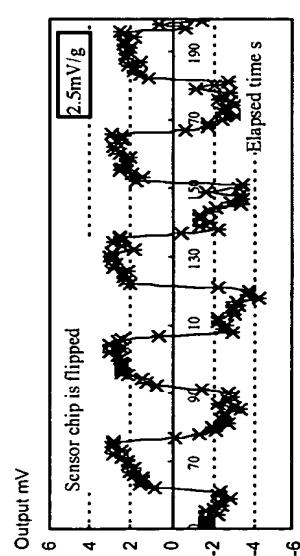


FIG. 5

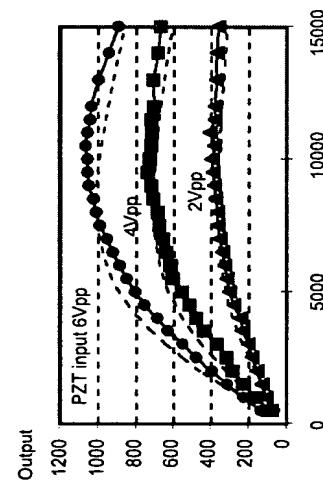


FIG. 6(a)

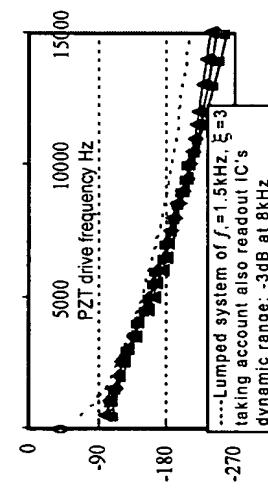


FIG. 6(b)

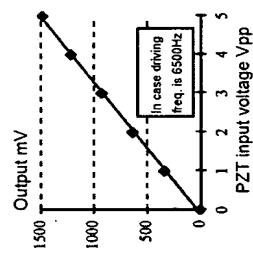


FIG. 7

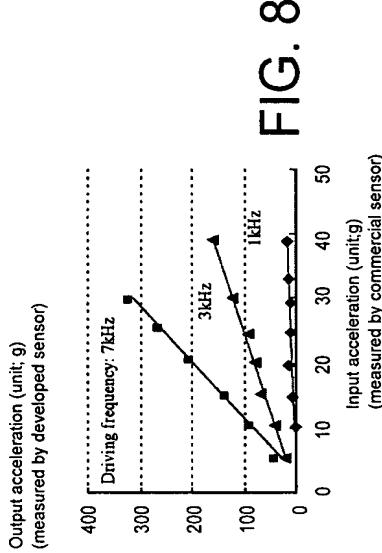


FIG. 8

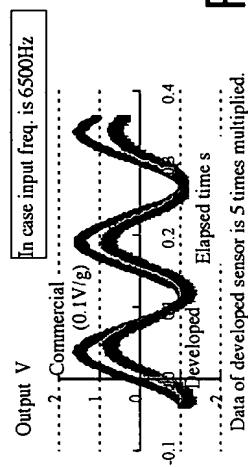


FIG. 9

8 / 11

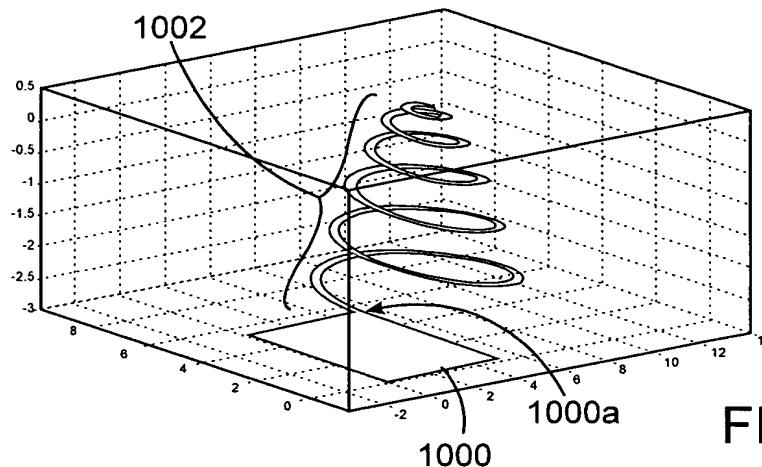


FIG.10(a)

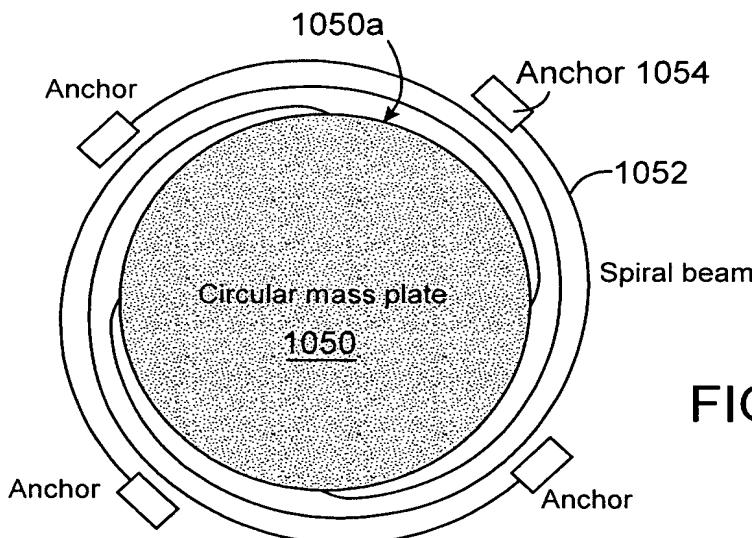


FIG.10(b)

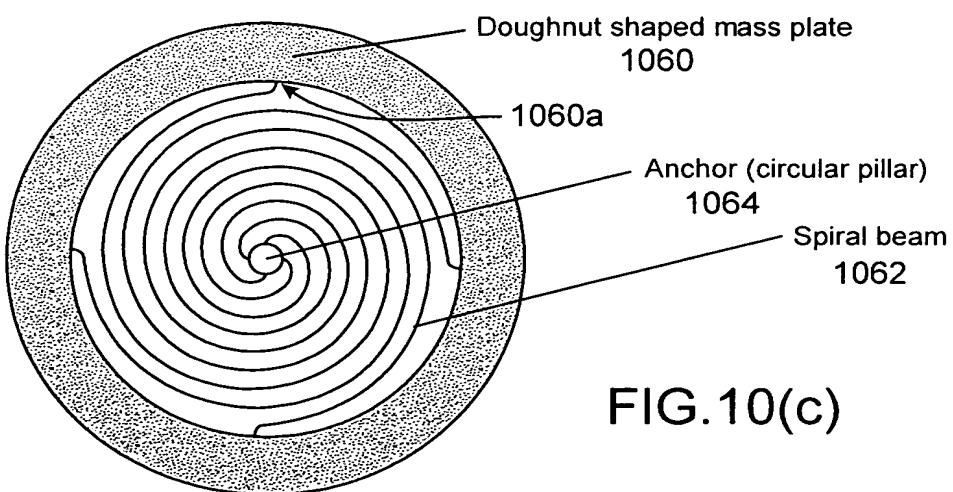


FIG.10(c)

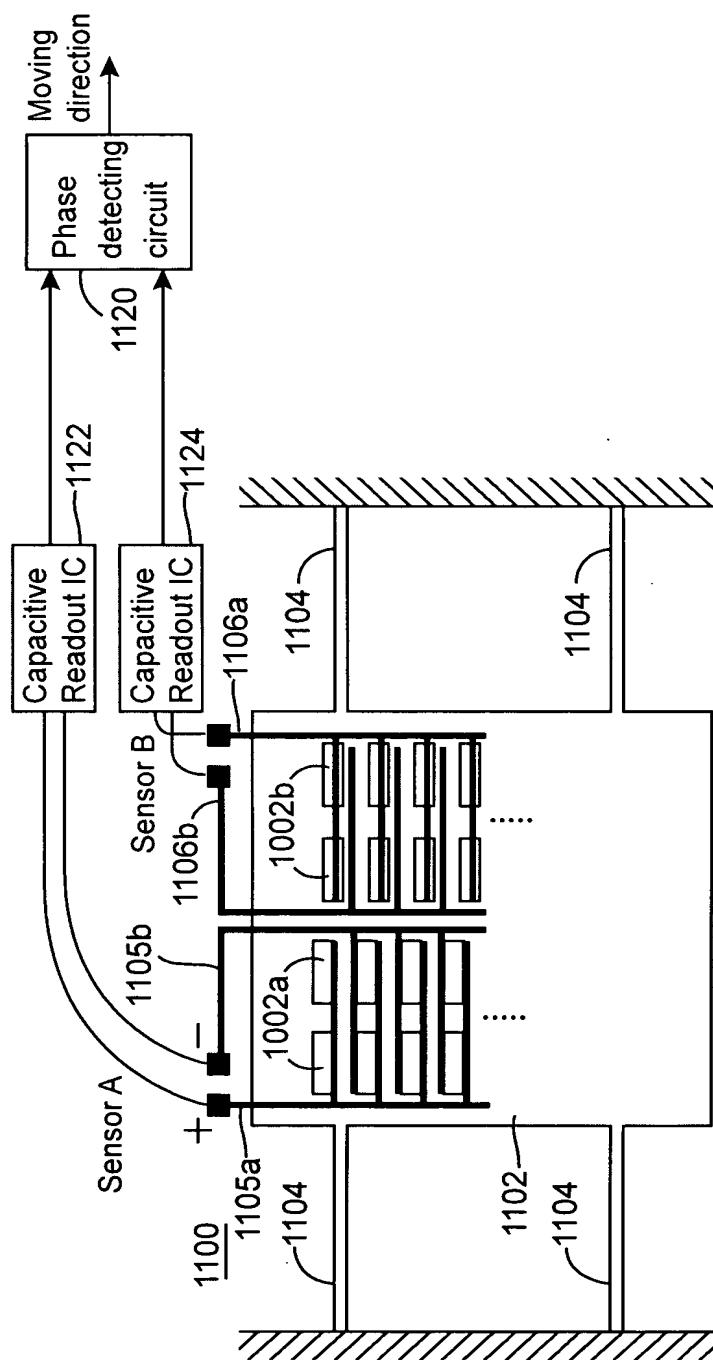


FIG.11

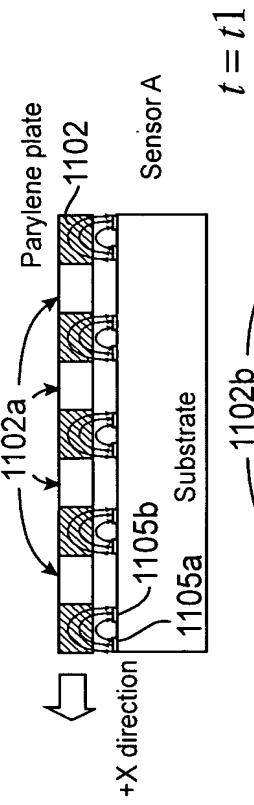


FIG. 12B

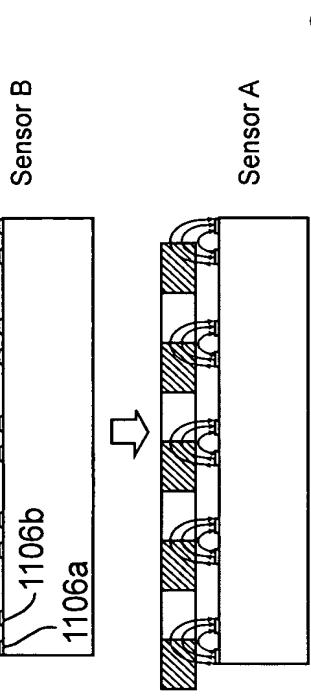


FIG. 12C

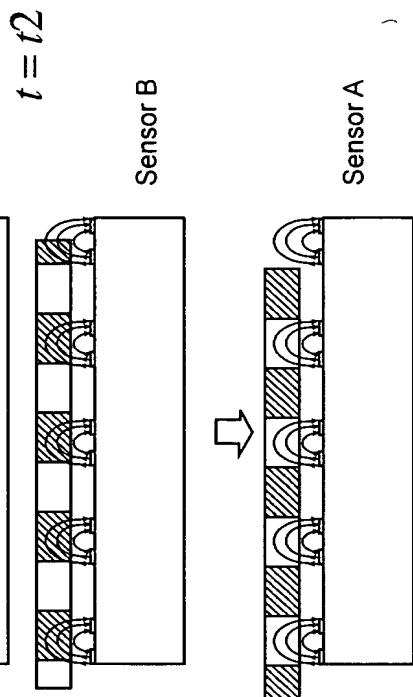


FIG. 12D

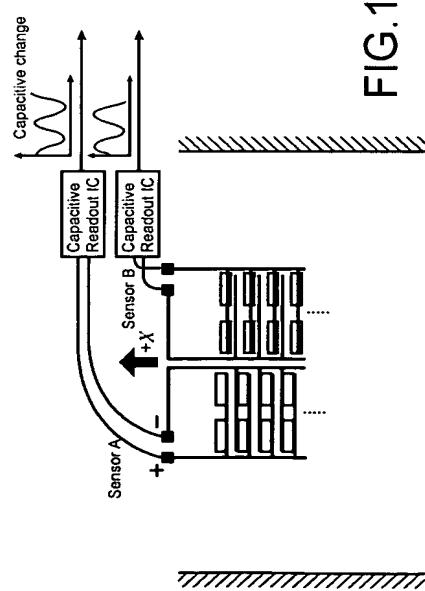
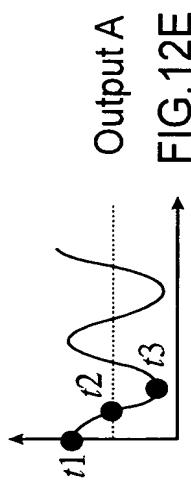
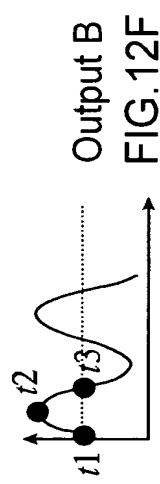


FIG. 12A

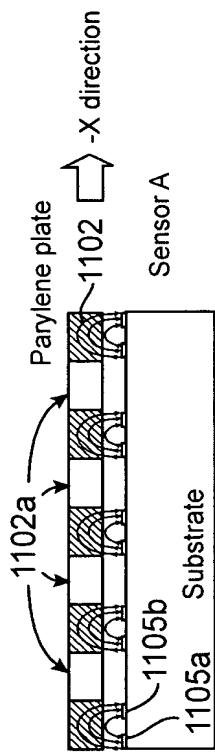


Output A



Output B

11 / 11

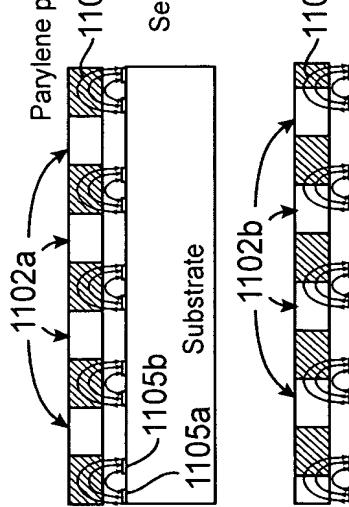


$t = t_1$

FIG. 13B

Sensor B

1102

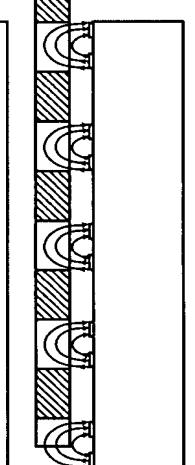


$t = t_2$

FIG. 13C

Sensor A

1102



$t = t_3$

FIG. 13D

Sensor B

1102

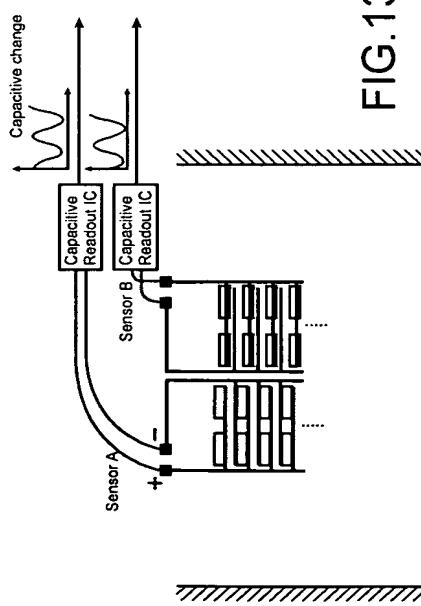
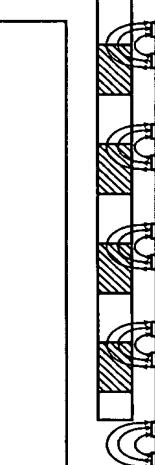
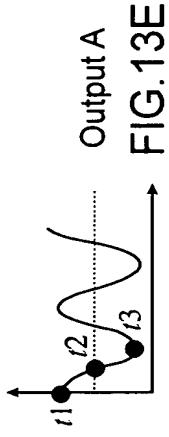


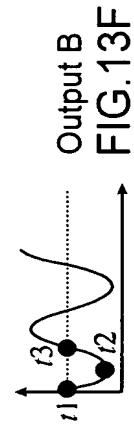
FIG. 13A

$\downarrow -x$



Output A

FIG. 13E



Output B

FIG. 13F